CS 600.226: Data Structures Michael Schatz

Nov 9, 2018

Lecture 30: Advanced Hash Tables



HW7

Assignment 7: Whispering Trees

Out on: November 2, 2018

Due by: November 9, 2018 before 10:00 pm

Collaboration: None

Grading:

Packaging 10%,

Style 10% (where applicable),

Testing 10% (where applicable),

Performance 10% (where applicable),

Functionality 60% (where applicable)

Overview

The seventh assignment is all about ordered maps, specifically fast ordered maps in the form of balanced binary search trees. You'll work with a little program called Words that reads text from standard input and uses an (ordered) map to count how often different words appear. We're giving you a basic (unbalanced) binary search tree implementation of OrderedMap that you can use to play around with the Words program and as starter code for your own developments.



HW8

Assignment 8: Competitive Spelling Bee

Out on: November 2, 2018

Due by: November 9, 2018 before 10:00 pm

Collaboration: None

Grading:

Packaging 10%,

Style 10% (where applicable),

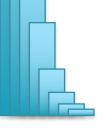
Testing 10% (where applicable),

Performance 30% (where applicable),

Functionality 40% (where applicable)

Overview

Your "one" task for this assignment is to take the simple spell checker we give you and to turn it into the fastest, most memory-efficient spell checker in the course, subject to the constraints detailed below. You are expected to do this by (once again) implementing the Map interface, this time using one of several hash table techniques (your choice, see below).



Part I: Hash Tables

Maps, Sets, and Arrays

Sets as Map<T, Boolean>

```
Mike -> True
Peter -> True
Joanne -> True
Zack -> True
Debbie -> True
Yair -> True
Ron -> True
```

Array as Map<Integer, T>

```
0 -> Mike
1 -> Peter
2 -> Joanne
3 -> Zack
4 -> Debbie
5 -> Yair
6 -> Ron
```

Maps are extremely flexible and powerful, and therefore are extremely widely used

Built into many common languages: Awk, Python, Perl, JavaScript...



Could we do everything in O(lg n) time or faster?

=> Balanced Search Trees

Hashing

$$Array[13] = 10; Array[42] = 15$$

0(1)

Array["Mike"] = 10; *Array["Peter"]* = 15

BST:O(lg n) -> Hash:O(1)

Hash Function enables Map<K, V> as Map<Integer, V> as Array<V>

- h(): K -> Integer for any possible key K
- h() should distribute the keys uniformly over all integers
- if k_1 and k_2 are "close", $h(k_1)$ and $h(k_2)$ should be "far" apart

Typically want to return a small integer, so that we can use it as an index into an array

- An array with 4B cells in not very practical if we only expect a few thousand to a few million entries
- How do we restrict an arbitrary integer x into a value up to some maximum value n?

$$0 \le x \% n \le n$$

Compression function: c(i) = abs(i) % length(a)

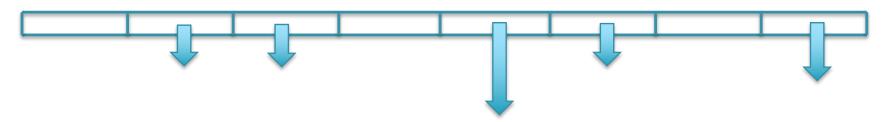
Transforms from a large range of integers to a small range (to store in array a)



Collision Strategies

1. Separate chaining:

More object overhead, but degrades gracefully as load approaches 1



2. Linear Probing

Minimal overhead, easy to implement, but tends to form large clusters



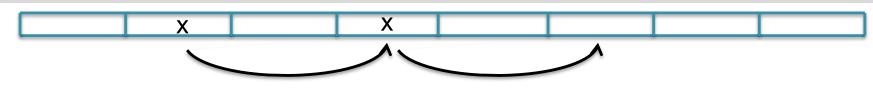
3. Quadratic Probing

Slightly more complex, but skips over larger and larger amounts to find holes



4. Double Hashing

Stride length depends on h₂(key)



(Bad) String Hash Functions

Hash Function enables Map<K, V> as Map<Integer, V> as Array<V>

- h(): K -> Integer for any possible key K
- h() should distribute the keys uniformly over all integers
- if k₁ and k₂ are "close", h(k₁) and h(k₂) should be "far" apart
- Should be fast, as we are aiming for O(1) performance
 - Unlike cryptographic hashes that are slow but give very few collisions

Hash of String: First char

- h(s) = (int) s.at(0)
- Super simple, but does not map to all possible integers, does not separate out values

Hash of String: sum of chars

$$h(s) = \sum_{i=0}^{s.length()-1} s.at(i)$$

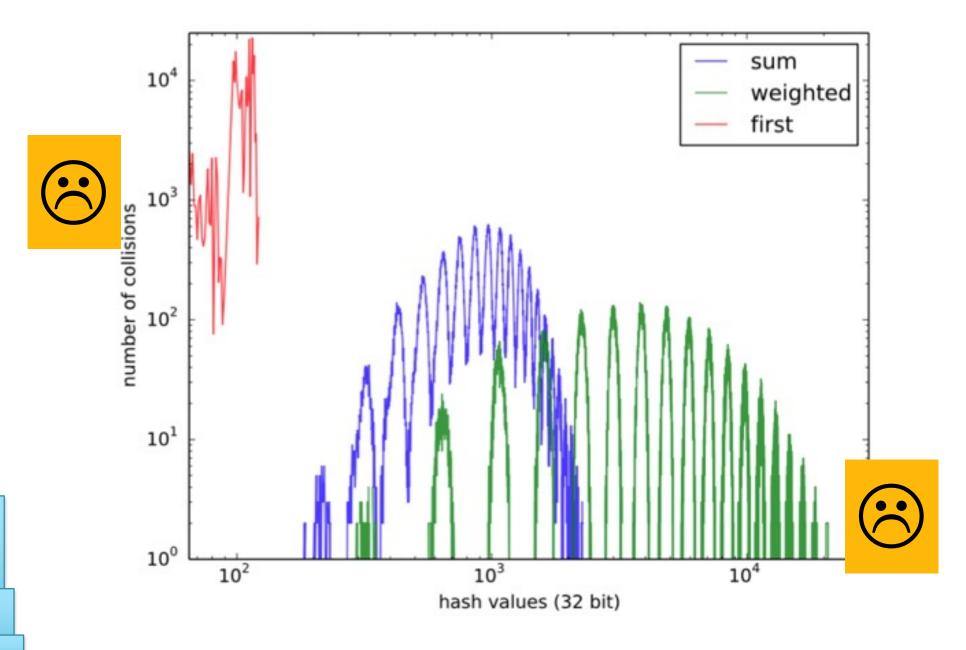
• Simple, but anagrams map to same value (stop, pots, tops, ..)

Hash of String: weighted sum of chars

$$h(s) = \sum_{i=0}^{s.length()-1} (i+1) \times s.at(i)$$

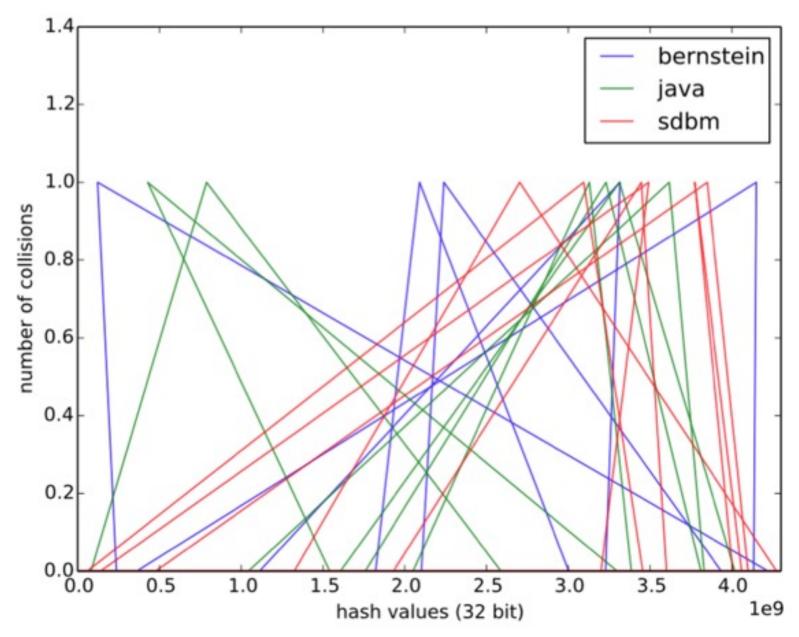
- Better: depends on both characters used and their order
 - Small values for typical words

Bad Hash Function Performance



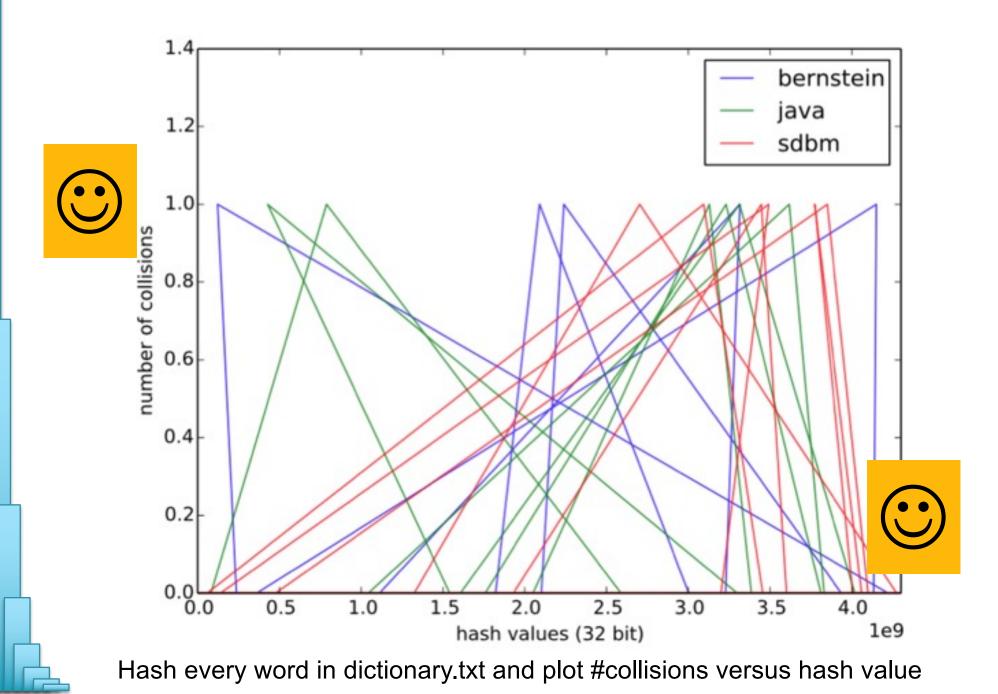
Hash every word in dictionary.txt and plot #collisions versus hash value

Good Hash Function Performance

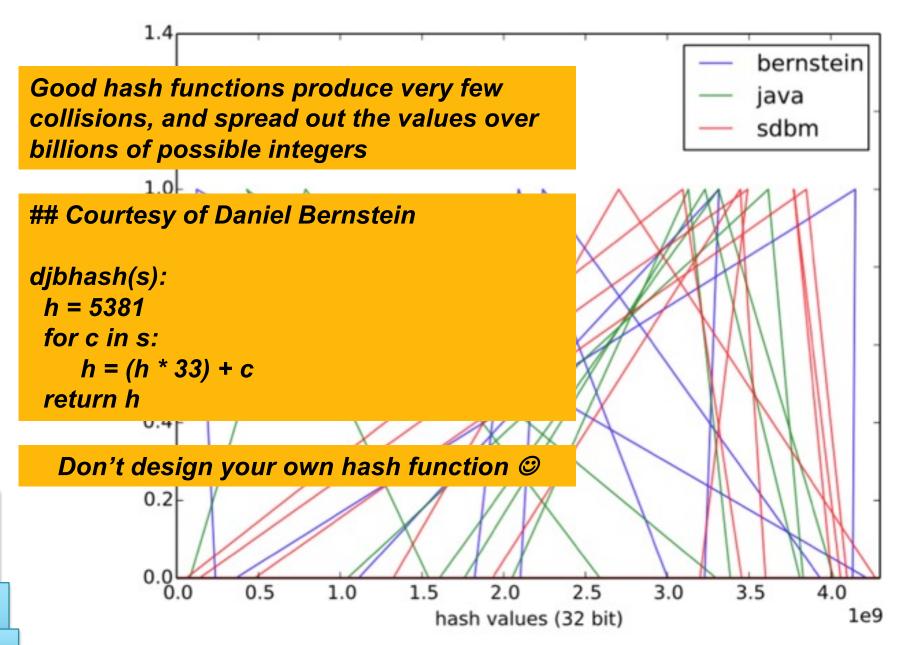




Good Hash Function Performance

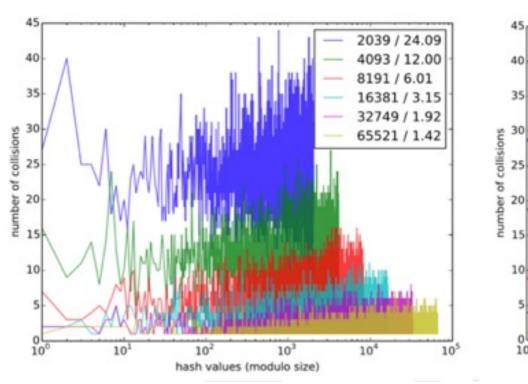


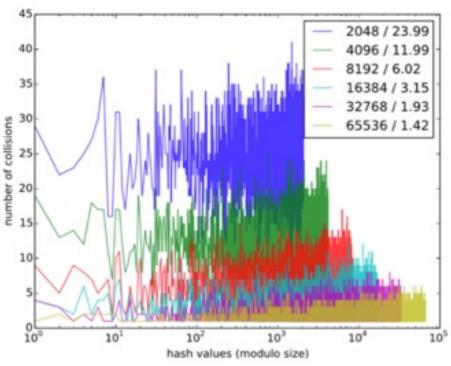
Good Hash Function Performance



Hash every word in dictionary.txt and plot #collisions versus hash value

Hash Table Size (Berstein Hash)





Prime Hash Table Sizes

Powers of Two

In theory, using a prime number as the size of your hash table will have fewer collisions, but in practice using powers of two works about as well.

The major exception is if you are using quadratic probing: with a load factor < 0.5, a prime size will guarantee you explore at least half of the possible slots, but a non-prime size make no guarantees



Part 3: HashMap Implementation

HashMap < K, V > (I)

```
import java.util.ArrayList;
import java.util.Iterator;
// doesn't resize/rehash
public class HashMap<K, V> implements Map<K, V> {
    private static class Entry<K, V> {
        K key;
        V value;
        Entry(K k, V v) {
             this.key = k;
             this.value = v;
        public boolean equals(Object that) {
            return (that instanceof Entry)
                && (this.key.equals(((Entry) that).key));
        public int hashCode() {
            return this.key.hashCode();
                           Use java hashCode()
```

Uses an
ArrayList<ArrayList>>
to store the data

Nested Entry<K,V> class

Equals checks the key only

Use java hashCode() function on the key For Strings:

$$h(s) = \sum_{i=0}^{n-1} s \, [\, i \,] \cdot 31^{n-1-i}$$

HashMap < K, V > (2)

```
// inner class, not nested! look ma, no static!
private class HashMapIterator implements Iterator<K> {
                                                               Iterator is a bit
    private int returned = 0;
                                                                complicated
    private Iterator<ArrayList<Entry<K, V>>> outer;
    private Iterator<Entry<K, V>> inner;
                                                             because it has to
    HashMapIterator() {
                                                              iterate over the
        this.outer = HashMap.this.data.iterator();
        this.inner = this.outer.next().iterator();
                                                             outer list buckets
                                                             and then the inner
    public boolean hasNext() {
        return this.returned < HashMap.this.size;
                                                           list of Entry's in each
                                                                   bucket
    public K next() {
        if (this.inner.hasNext()) {
            this.returned += 1;
            return this.inner.next().key;
        } else {
            while (!this.inner.hasNext() && this.outer.hasNext()) {
                this.inner = this.outer.next().iterator();
            if (this.inner.hasNext()) {
                this.returned += 1;
                return this.inner.next().key;
            } else {
                return null;
    public void remove() {
        throw new UnsupportedOperationException();
```

HashMap<K,V> (3)

```
private static final int INITIAL SIZE = 8;
                                                       Use 8 buckets,
private ArrayList<ArrayList<Entry<K, V>>> data;
                                                      initialized with an
private Entry<K, V> fake;
                                                      empty list in each
private int size;
public HashMap() {
    this.data = new ArrayList<>(); // Java 7
    for (int i = 0; i < INITIAL SIZE; i++) {
        this.data.add(new ArrayList<Entry<K, V>>());
    this.fake = new Entry<K, V>(null, null);
}
public boolean has(K k) {
                                              fake helps with searching
    return this.find(k) != null;
                                                   so we can call
                                              ArrayList.indexOf() which
private Entry<K, V> find(K k) {
                                                 uses Entry.equals()
    int slot = this.hash(k);
    this.fake.key = k;
    int index = this.data.get(slot).indexOf(this.fake);
    if (index == -1) {
        return null;
    } else {
        return this.data.get(slot).get(index);
```

HashMap<K,V> (4)

```
private int hash(Object o) {
    return this.abs(o.hashCode()) % this.data.size();
                                                 hash() returns
private int abs(int i) {
                                          hashCode % num_buckets
    if (i < 0) {
        return -i;
    } else {
        return i;
public void put(K k, V v) throws UnknownKeyException {
    Entry<K, V> e = this.findForSure(k);
    e.value = v;
public V get(K k) throws UnknownKeyException {
    Entry<K, V> e = this.findForSure(k);
    return e.value;
```

findForSure guarantees the reference is not null



HashMap < K, V > (5)

```
private Entry<K, V> findForSure(K k) throws UnknownKeyException {
     Entry<K, V> e = this.find(k);
     if (e == null) {
                                               findForSure guarantees the
         throw new UnknownKeyException();
                                                   reference is not null
     return e;
 public void insert(K k, V v) throws DuplicateKeyException {
     if (this.has(k)) {
         throw new DuplicateKeyException();
     Entry<K, V> e = new Entry<K, V>(k, v);
     int slot = this.hash(k);
     this.data.get(slot).add(e);
     this.size += 1;
 public V remove(K k) throws UnknownKeyException {
     Entry<K, V> e = this.findForSure(k);
     int slot = this.hash(k);
     this.data.get(slot).remove(e);
     this.size -= 1;
     return e.value;
 public Iterator<K> iterator() {
     return new HashMapIterator();
```

Just adds the item to the appropriate bucket, but does **NOT** resize!

Removes the item from the containing bucket using ArrayList.remove



Benchmarks

BinarySearchTreeMap

```
## These are the standard, unbalanced binary search trees.
$ java Words <manifesto.txt >bla
0.527914894
$ java Words <wealth.txt >bla
1.629583552
$ java Words <war.txt >bla
1.865477425
$ java -Xss2048k Words <cracklib.txt >bla
43.321007802
$ java -Xss16384k Words <dictionary.txt >bla
2905.769206485
```

HashMap

```
## First for a bucket array with only eight slots
```

```
$ java Words <manifesto.txt >bla
```

- 0.612431685
- \$ java Words <wealth.txt >bla
- 4.413707022
- \$ java Words <war.txt >bla
- 7.679160966
- \$ java Words <cracklib.txt >bla
- 16.050761321
- \$ java Words <dictionary.txt >bla

541.798612936

Even a small hash table outperforms a naïve BST



Benchmarks

```
HashMap
## Now for 4096 slots
## That's still a pretty high load factor:
## dictionary.txt has 234937 distinct words so alpha = 57.36
$ java Words <manifesto.txt >bla
0.529792145
$ java Words <wealth.txt >bla
1.485476444
$ java Words <war.txt >bla
1,647926909
$ java Words <cracklib.txt >bla
1.562509081
$ java Words <dictionary.txt >bla
4,221646673
AvlTreeMap
```

```
$ java Words <manifesto.txt >bla
0.64004931
$ java Words <wealth.txt >bla
1.744705285
$ java Words <war.txt >bla
2.062956075
$ java Words <cracklib.txt >bla
2.256693694
$ java Words <dictionary.txt >bla
7.379325237
```

HashMap is noticeably faster than AVLTreeMap even though AVLTreeMap guarantees O(lg n) performance



Benchmarks

```
HashMap
## Now for 4096 slots
## That's still a pretty high load factor:
## dictionary.txt has 234937 distinct words so alpha = 57.36
$ java Words <manifesto.txt >bla
0.529792145
$ java Words <wealth.txt >bla
1,485476444
$ java Words <war.txt >bla
1,647926909
$ java Words <cracklib.txt >bla
1.562509081
$ java Words <dictionary.txt >bla
4,221646673
TreapMap
```

```
$ java Words <manifesto.txt >bla
0.543315182
$ java Words <wealth.txt >bla
1.788253795
$ java Words <war.txt >bla
2.196759232
$ java Words <cracklib.txt >bla
1.5308888
$ java Words <dictionary.txt >bla
3.602697315
```

The only thing faster than HashMap is the TreapMap

Random almost always wins ©



Part 4: Advanced Topics

Separate Chaining Analysis

Assume the table has just 1 cell:

All n items will be in a linked list => O(n) insert/find/remove ⊗

Assume the hash function h() always returns a constant value

All n items will be in a linked list => O(n) insert/find/remove ☺

Assume table has m cells AND h() evenly distributes the keys

- Every cell is equally likely to be selected to store key k, so the n items should be evenly distributed across m slots
- Average number of items per slot: n/m
 - Also called the *load factor* (commonly written as α)
 - Also the probability of a collision when inserting a new key
 - Empty table: 0/m probability
 - After 1st item: 1/m
 - After 2nd item: 2/m

Expected time for unsuccessful search:

O(1+n/m)

Expected time for successful search:

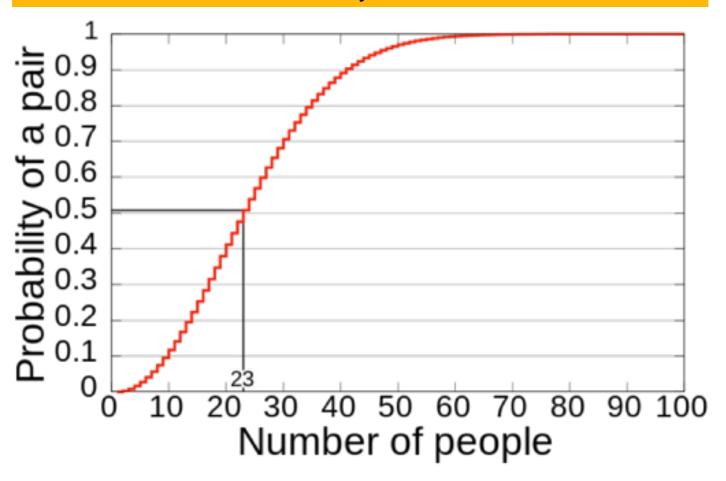
O(1+n/m/2) => O(1+n/m)

If n < c*m, then we can expect constant time! @



Birthday Paradox

Some collisions are essentially unavoidable at modest load

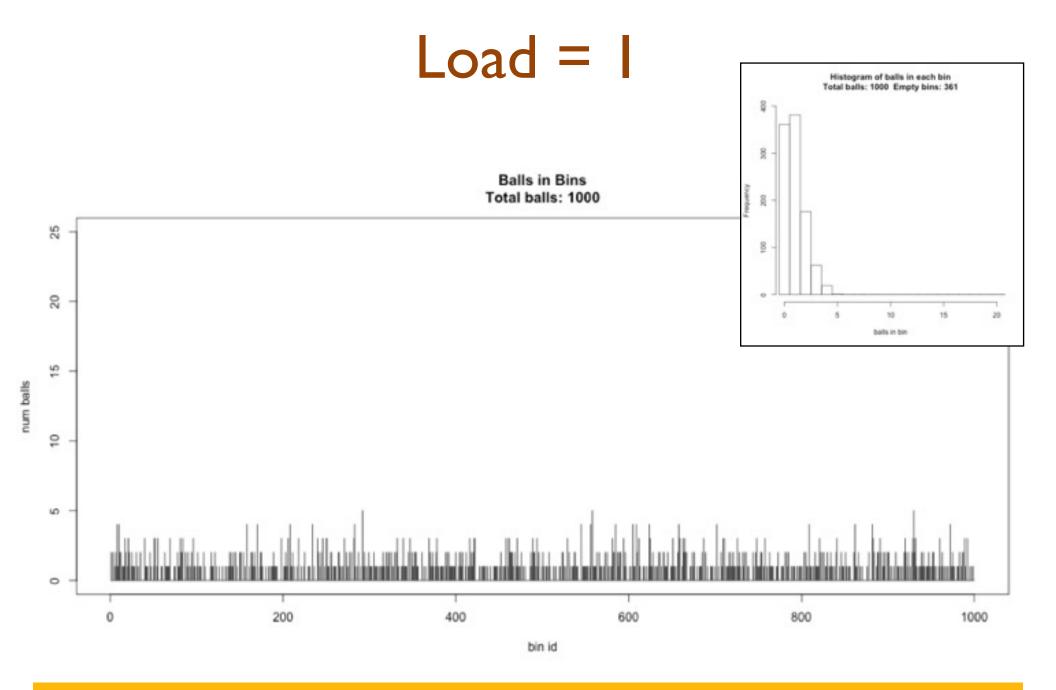


There is a 364/365 chance 2 people don't share the same birthday There is a 364/365 * 363/365 chance 3 people don't share There is a 364/365 * 363/365 * 362/365 chance 4 people don't share

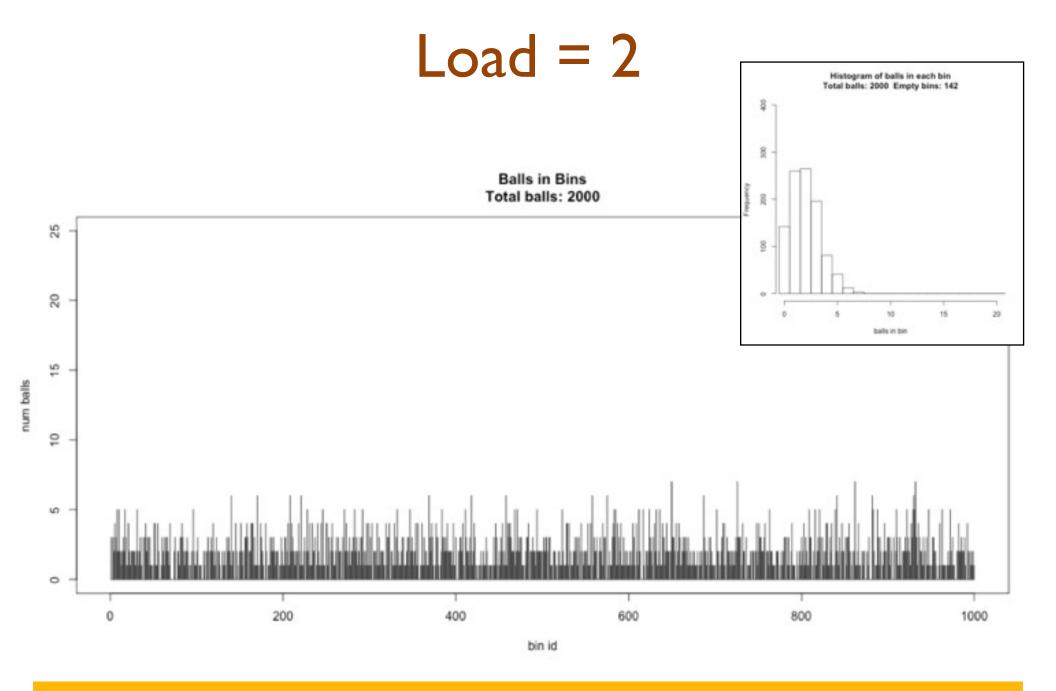
...

There is a >90% chance two people in this room share the same birthday

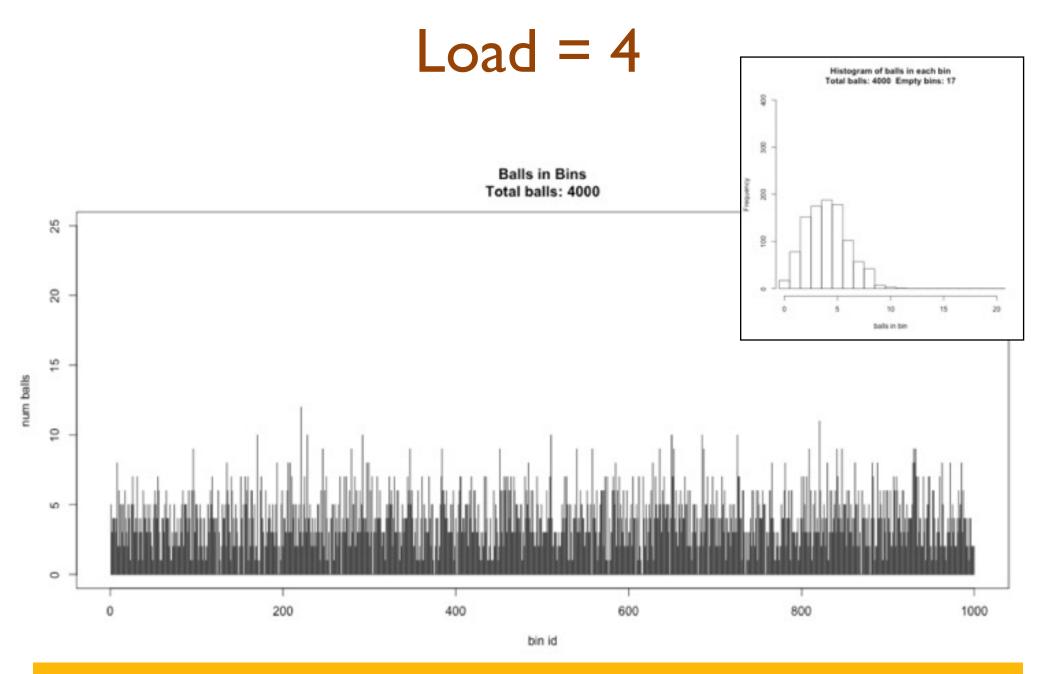




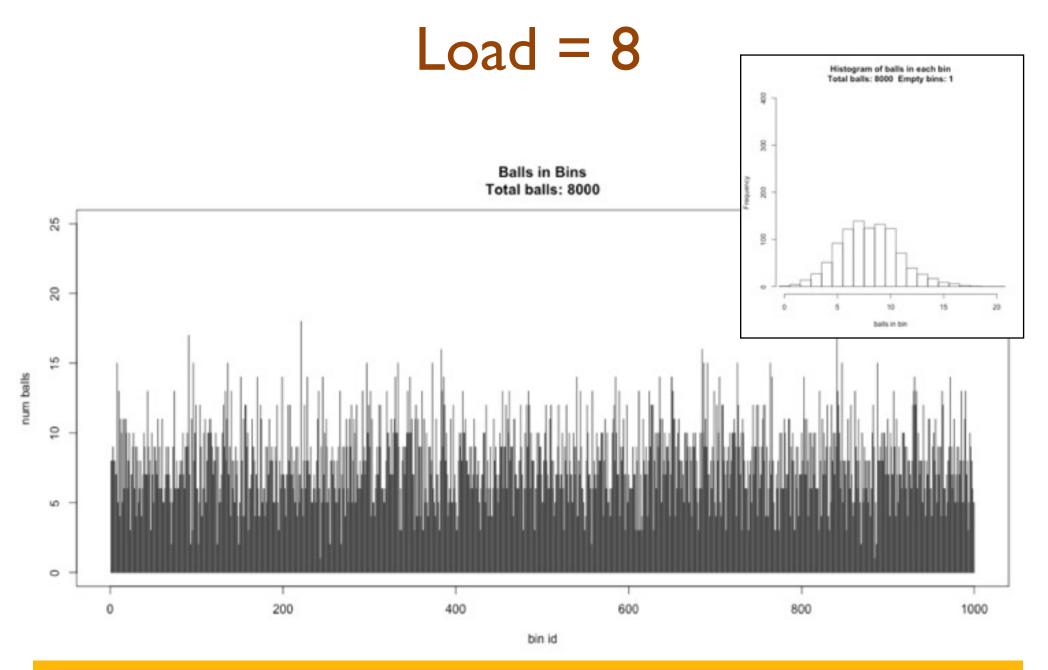
On average, there will be 1 entry per cell, but by random chance about 35% of the slots are empty, about 38% have 1 entry, and 27% have 2 or more



On average, there will be 2 entries per cell, but by random chance ~15% of the slots are empty, ~25% have 1 entry, ~26% have 2 entries, and 34% have 3 or more



On average, there will be 4 entries per cell, but by random chance ~2% of the slots are empty, ~8% have 1 entry, ~15% have 2, 17% have 3, 18% have 4, and 40% have more than 4



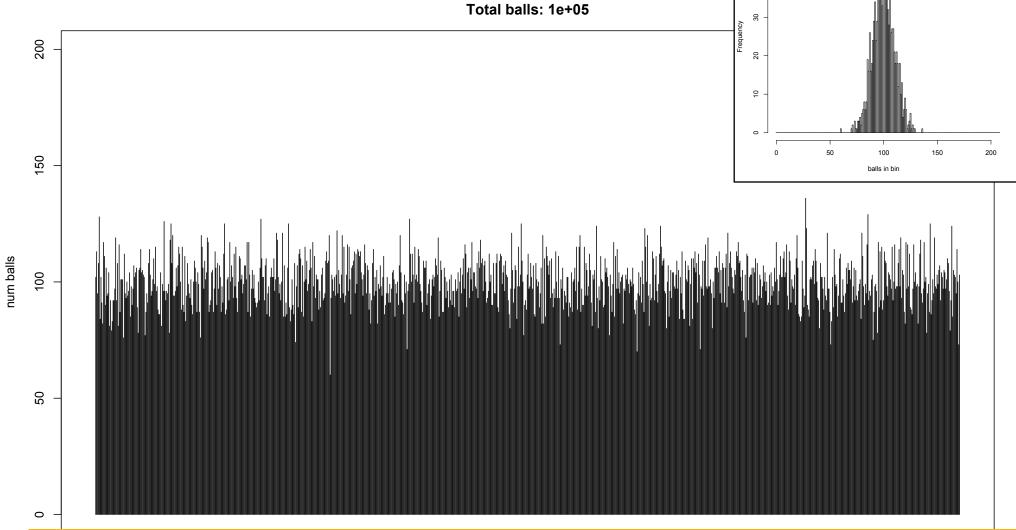
On average, there will be 8 entries per cell, but by random chance ~0.1% of the slots are empty, about ~30% have over 8, and some may have 20 entries

Load = 100

Balls in Bins Total balls: 1e+0 Histogram of balls in each bin Total balls: 1e+05 Empty bins: 0

20

4



At high load we expect every slot to be used, although some slots may have 150 or more entries

Poisson Distribution

The probability of a given number of events occurring in a fixed interval of time and/or space if these events occur with a known average rate and independently of the time since the last event.

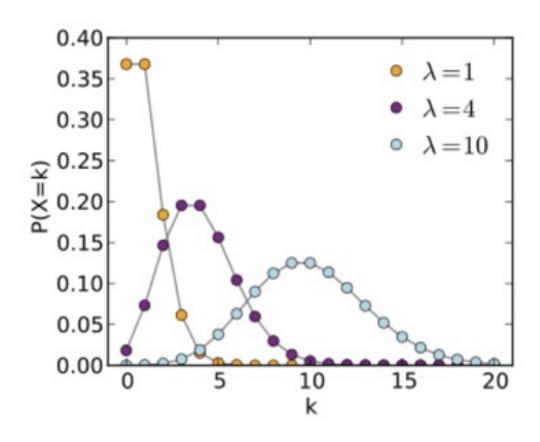
Formulation comes from the limit of the binomial equation

Resembles a normal distribution, but over the positive values, and with only a single parameter.

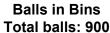
Key property:

The standard deviation is the square root of the mean.

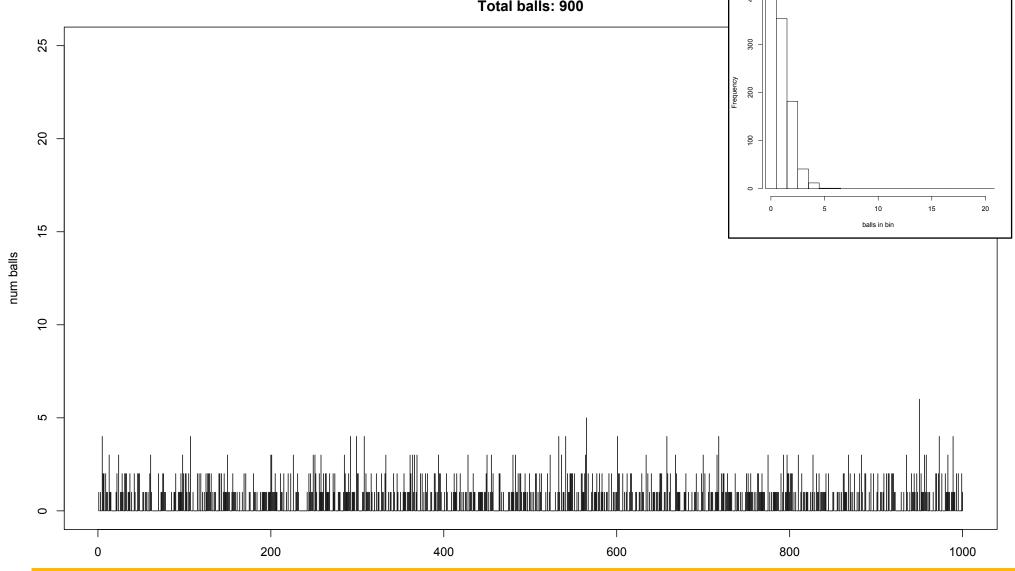
$$P(k) = \frac{\lambda^k}{k!} e^{-\lambda}$$



Load = .9



Histogram of balls in each bin Total balls: 900 Empty bins: 409



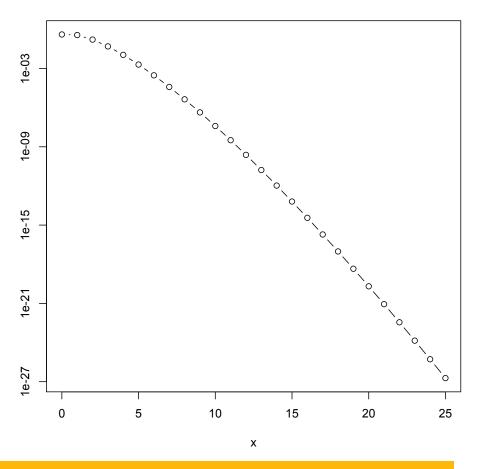
With 90% load, about 40% of the slots will be empty and most buckets have <5 entries

Load = .9

Probability of x balls in a single bin (load=0.9)

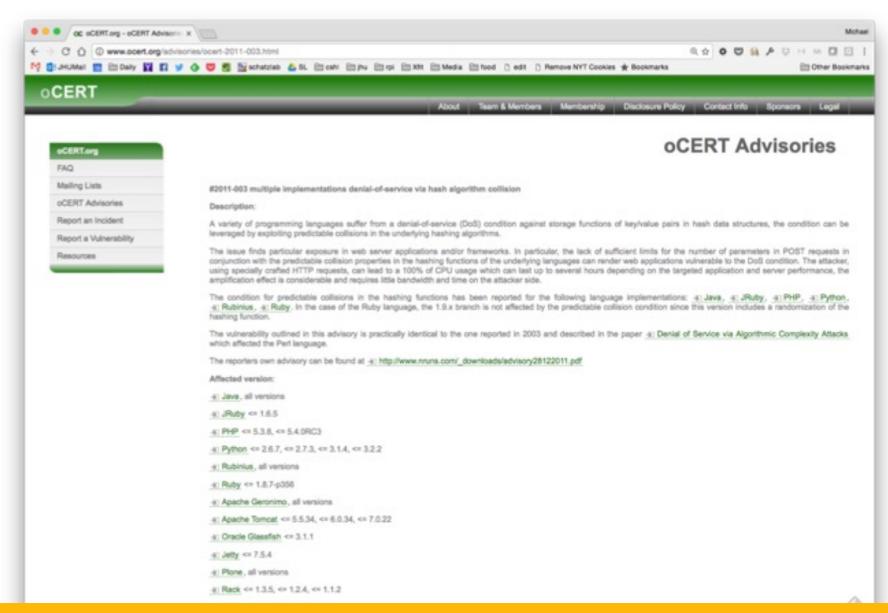
0.3 0.2 0.7 0.0 5 10 15 20 25 Х

Probability of x balls in a single bin (load=0.9)



Probabilities get exceedingly small to have large number of entries in 1 bucket Expected worse-case cost of a lookup in a chained hash table is O(lg n / lg lg n)

Denial of Service Attacks



However, if an adversary knows what kind of hash table we are using, can force all the entries into a single bucket and slow everything down to linear time

Perfect hashing

Perfect Hashing

- If all keys are known ahead of time, a perfect hash function can be constructed to create a perfect hash table that has no collisions.
- Perfect hashing allows for constant time lookups in all cases
- The original construction of Fredman, Komlós & Szemerédi (1984) uses a two-level scheme to map a set S of n elements to a range of O(n) indices, and then map each index to a range of hash values.
 - Relatively expensive to compute: key parameters found in polynomial time by choosing values randomly until finding one that works; but once computed can be used over and over and over again ☺
 - The hash function requires O(n) storage space

Minimal Perfect Hashing

- If minimal perfect hashing is used, every slot in the hash table is used
- The best currently known minimal perfect hashing schemes can be represented using approximately 2.6 bits per key

Guaranteed constant time and linear space lookups @



Universal hashing

Universal Hashing

- If all keys are not known ahead of time, an adversary may pick the keys so that all of them hash to the same bin!
- Even without an adversary, you may get unlucky and you will have more collisions than desired, but just rehashing the data with the same function wont help
- The solution to these problems is to pick a function randomly from a family of hash functions!
 - A family of functions H = {h : U -> |m| } is called a universal family if

$$orall x,y\in U,\; x
eq y: \quad \Pr_{h\in H}[h(x)=h(y)]\leq rac{1}{m}.$$

Universal Hash Function for Integers

 The original proposal of Carter and Wegman (1979) was to pick a prime p > m and define:

$$h_{a,b}(x) = ((ax+b) \mod p) \mod m$$

where a,b and randomly chosen integers modulo p







Cuckoo Birds

These species are *obligate brood parasites*, meaning that they only *reproduce by laying their eggs in the nests of other birds*. The best-known example is the European common cuckoo.

The cuckoo egg hatches earlier than the host's, and the cuckoo chick grows faster; in most cases the chick evicts the eggs or young of the host species.

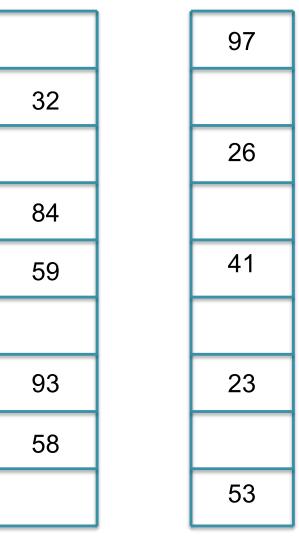
The chick has no time to learn this behavior, so it must be an instinct passed on genetically. The chick encourages the host to keep pace with its high growth rate with its rapid begging call and the chick's open mouth which serves as a sign stimulus.





- Worst case O(1) look up @
- Worse case O(1) remove @
- Insertions are usually O(1), but occasionally need to rehash everything in O(n) steps => expected O(1) ☺
- Uses two simple hash functions, h₁ and h₂, from a universal family and two tables T₁ and T₂ ©
- Keys can be stored at h_1 in T_1 or h_2 in $T_{2,}$ but no where else! :-?
- If those cells are already filled, kick out one of the existing keys and shift that key to its alternate location :-!
- Repeat until every key has been correctly shifted or until no solution is found – if no solution is found, rehash everything with different random hash functions in O(n) time ©

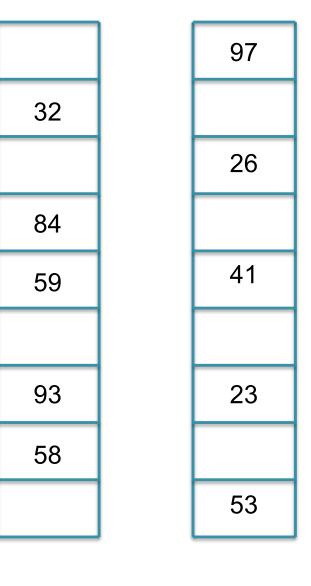
Pagh & Rodler, 2001



 T_2/h_2

 T_1/h_1

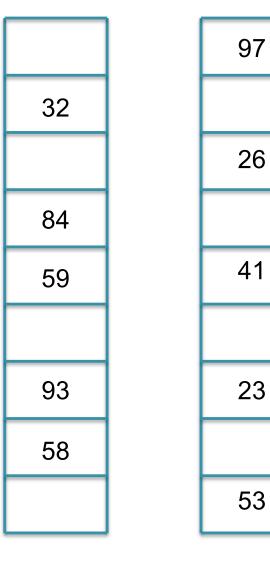
- To insert an element x, start by attempting to insert it into table 1
- If h₁(x) is empty, place x there
- Otherwise place x there, evict the old element y, and try placing y into table at h₂
- Repeat this process bouncing between tables until all elements stabilize
- If the locations don't stabilize quick enough (O(lg n)) rehash the table





 T_1/h_1

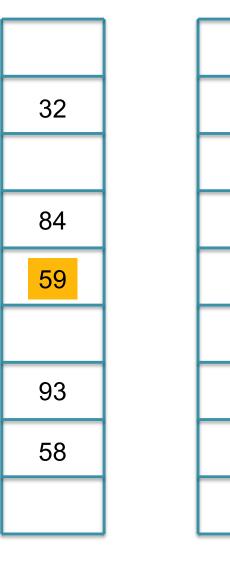
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insert(42)

 T_1/h_1

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 T_1/h_1



 T_2/h_2

97

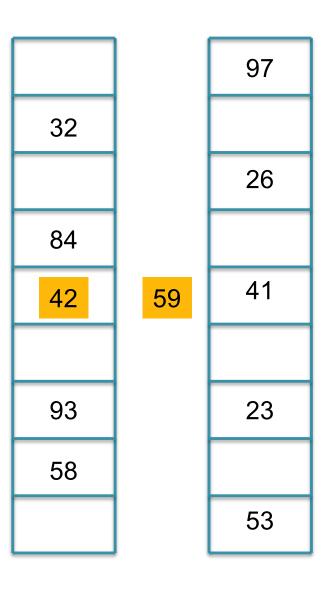
26

41

23

53

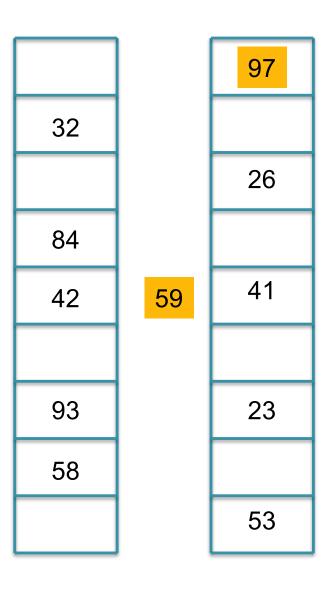
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insert(42)

 T_1/h_1

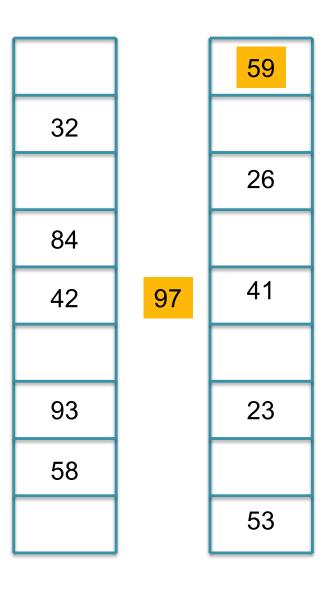
- To insert an element x, start by attempting to insert it into table 1
- If h₁(x) is empty, place x there
- Otherwise place x there, evict the old element y, and try placing y into table at h₂
- Repeat this process bouncing between tables until all elements stabilize
- If the locations don't stabilize quick enough (O(lg n)) rehash the table



insert(42)

 T_1/h_1

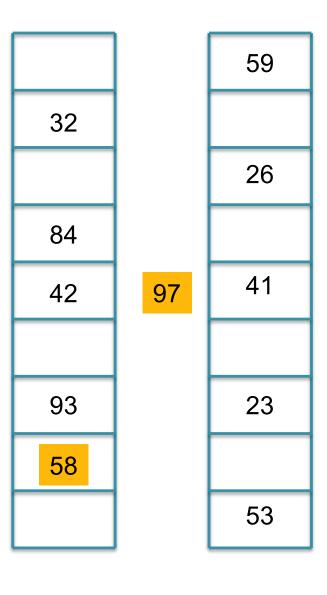
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insert(42)

 T_1/h_1

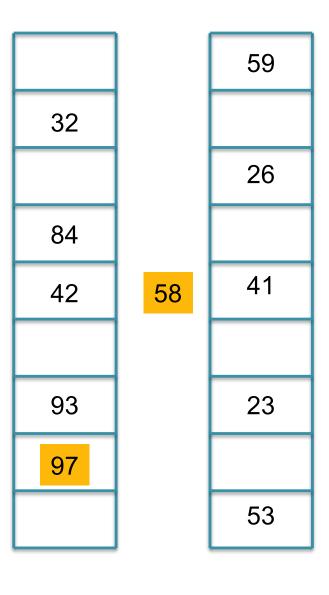
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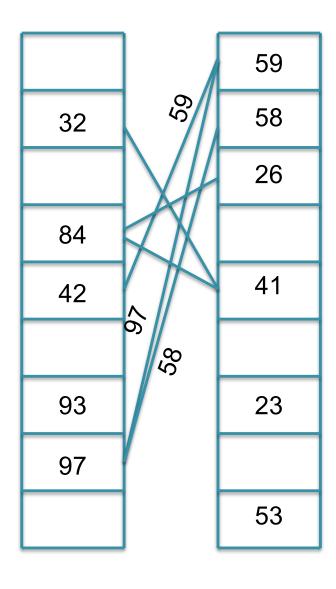


insert(42)

 T_1/h_1

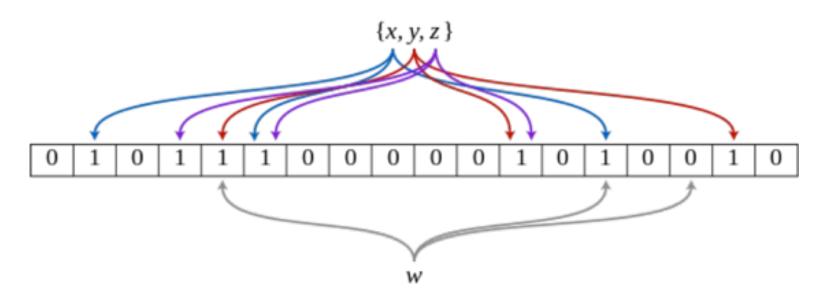
Cuckoo Graph

- Analyzing the performance is complicated because:
 - Elements can move around and bin in one of two different places
 - The sequence of displacements can jump chaotically over the table
- Overcome these challenges by analyzing paths of the cuckoo graph
 - Each table slot is a node
 - Each element is an edge
 - Edges link where each element can be
 - Each insertion introduces a new edge
- Tricky, but by analyzing the structure and paths of the cuckoo graph, can prove the amortized cost of an insertion is O(1 + e)



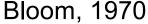
 T_1/h_1



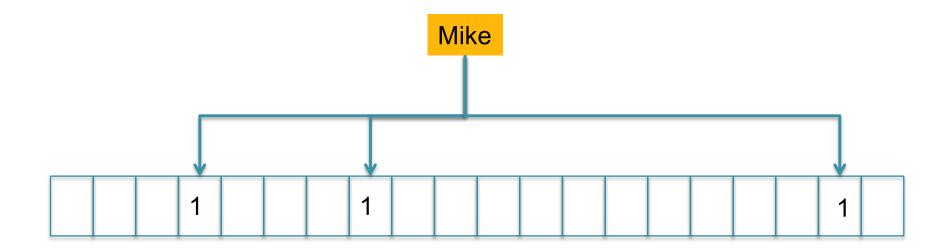


Extremely space efficient data structure for recording members of a set

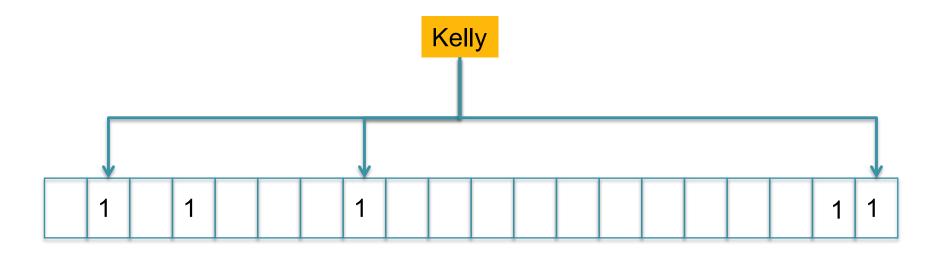
- Uses just a few *bits* in a bit array to record that a key is or is not in the set, independent of the size or number of elements in the set
- Works by applying a small number (k) of hash functions to the key and checking those cells of the bit array
- Initialize bit array to all false; Insert an element set by setting the appropriate bits to true as determined by the k hash functions: O(1) time
- If any of the bits are false, the key is definitely not in the set! O(1) time
- If all of the bits are true, the key is *probably* in the set: O(1) time



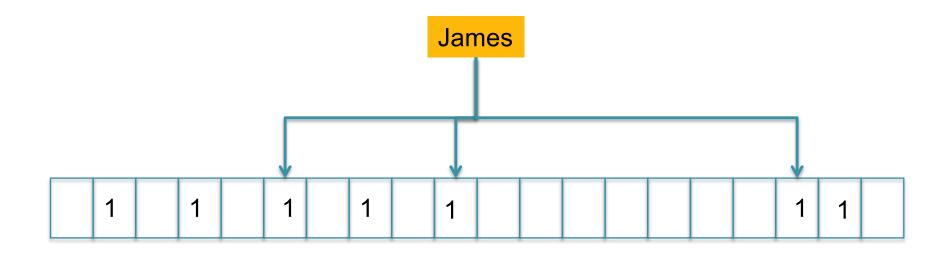
• Insert the following values: Mike, Kelly, James, Katherine, Sydney



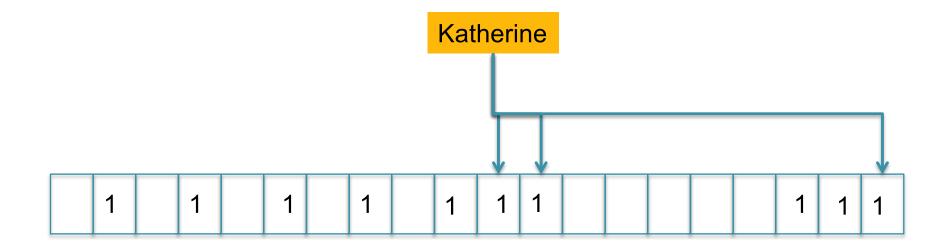
• Insert the following values: Mike, Kelly, James, Katherine, Sydney



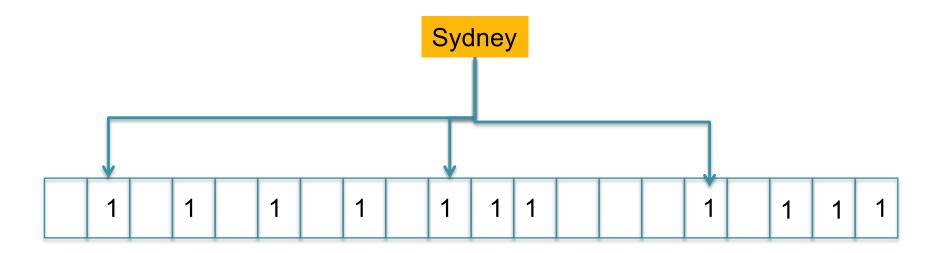
• Insert the following values: Mike, Kelly, James, Katherine, Sydney



Insert the following values: Mike, Kelly, James, Katherine, Sydney



Insert the following values: Mike, Kelly, James, Katherine, Sydney



- My entire family is loaded using 20 bits instead of 29 characters!
 - Order of magnitude reduction in space is very common
- As many as 3*5=15 bits could be true
 - But only 11 are actually set to true

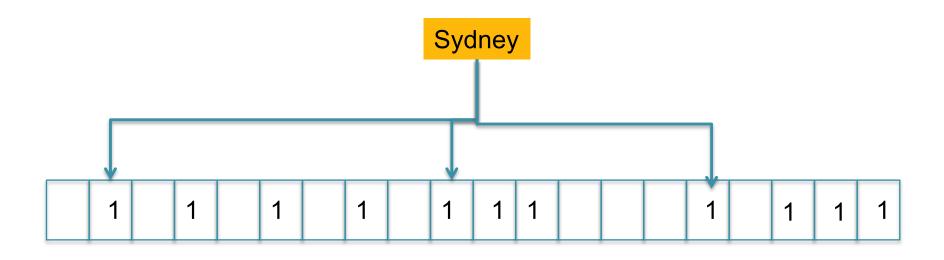
1	1	1	1	1	1	1		1	1	1	1

Is Sydney in the set?

Sydney



Is Sydney in the set?



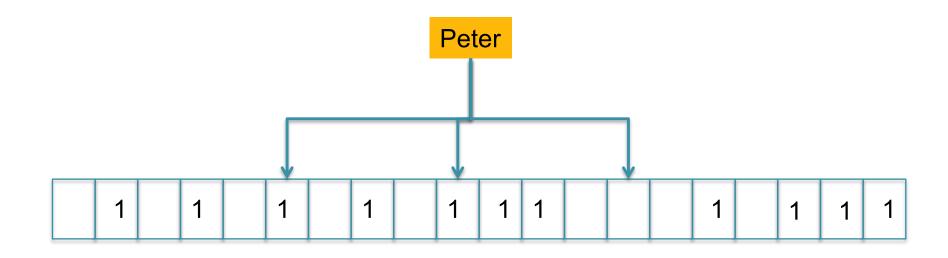


• Is Peter in the set?

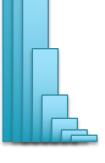
Peter



Is Peter in the set?



Definitely not!

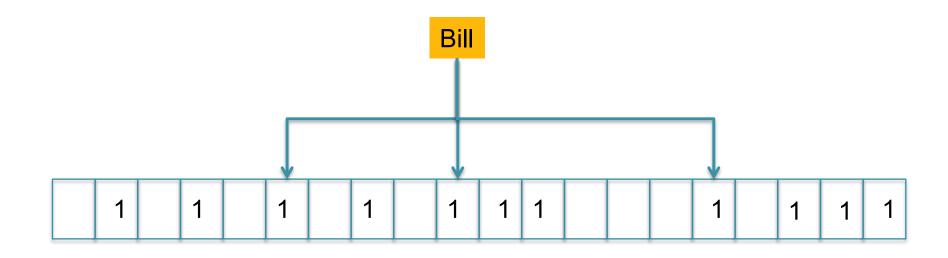


• Is Bill in the set?

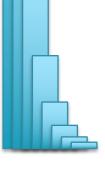
Bill



Is Bill in the set?



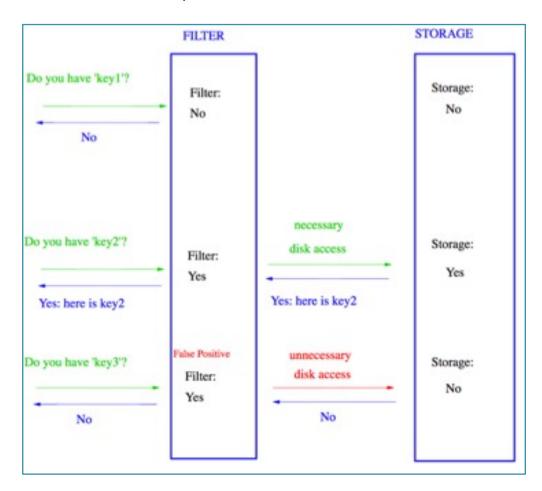
Hmm... I think so, but not totally sure :-/

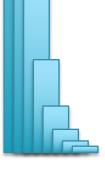


Why Bloom Filters?

When a Bloom filter returns no, we are certain that it is not present, allowing us to skip unnecessary work

- Disk is ~100,000x slower than RAM
- What it says yes, we might be "tricked" with a false positive
 - Either do a more expensive check, or accept your result may have a (small) amount of error)





How many false positives?

Assume a single hash function picks a cell with probability 1/m

- Probability that it doesn't pick the cell: 1-1/m
- Probability that all k hashes don't pick the cell: (1-1/m)^k
- Probability that a certain bit is 0 after n insertions: (1-1/m)^{kn}

Probability that a certain bit is 1 after n insertions:

$$1-\left(1-\frac{1}{m}\right)^{kn}$$

Probability that all k bits will be set by chance: the false positive rate

$$\left(1-\left[1-rac{1}{m}
ight]^{kn}
ight)^kpprox \left(1-e^{-kn/m}
ight)^k$$

Size of table to guarantee a desired false positive rate

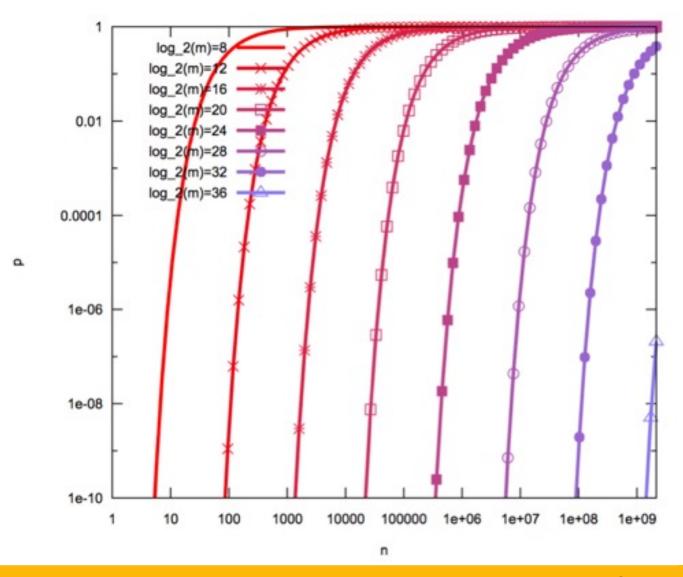
$$m=-rac{n\ln p}{(\ln 2)^2}$$

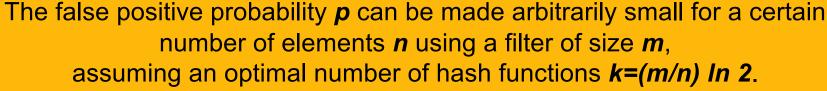
Optimal number of hash functions

$$k=rac{m}{n}\ln 2$$



How many false positives?







Bloom Filters Union

Schatz Family



+ Frohlich Family



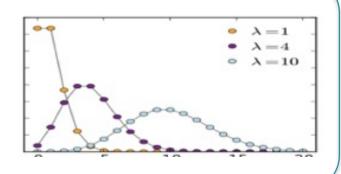
Schatz+Frohlich Family



Advanced Hashing Summary

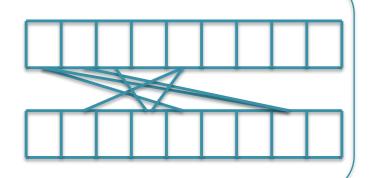
Collisions

- Be careful of collisions!
- Perfect hashing guarantees we avoid collisions, universal hashing lets us pick a new hash function from a family as needed



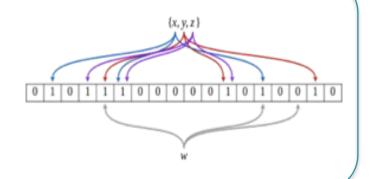
Cuckoo Hashing

- Simple open addressing technique with O(1) lookup with expected O(1) insert
- Often outperforms other collision management schemes



Bloom Filters

- Store a huge set in a tiny amount of space allowing for a small rate of false positives.
- Used as a quick pre-filter to determine if the slow operation needs to take place



Next Steps

- I. Reflect on the magic and power of Hash Tables!
- 1. Assignment 8 due Friday November 16 @ 10pm